Deep Multi-Task and Meta Learning cs 330

The Plan for Today

1. Course goals & logistics

Key learning today: what is multi-task learning??

- 2. Why study multi-task learning and meta-learning?

Introductions



Amelie Byun Chelsea Finn Course Coordinator Instructor



Ansh Khurana Head TA



Yoonho Lee TA



Alex Sun ΤA



Max Sobol Mark TA



Welcome!

First question: How are you doing? (answer by raising hand)

Information & Resources

Course website: <u>http://cs330.stanford.edu/</u>

Ed: Connected to Canvas

Staff mailing list: cs330-staff-aut2324@lists.stanford.edu

Office hours: Check course website & Canvas, *start today*.

OAE letters can be sent to staff mailing list or in private Ed post.

We have put a lot of info here Please read it. :)

What will you learn in this course?

- 1. The foundations of modern deep learning methods for learning across tasks
- 2. How to implement and work with practical multi-task & transfer learning systems (in PyTorch)
- 3. A glimpse into the scientific and engineering process of building and understanding new algorithms

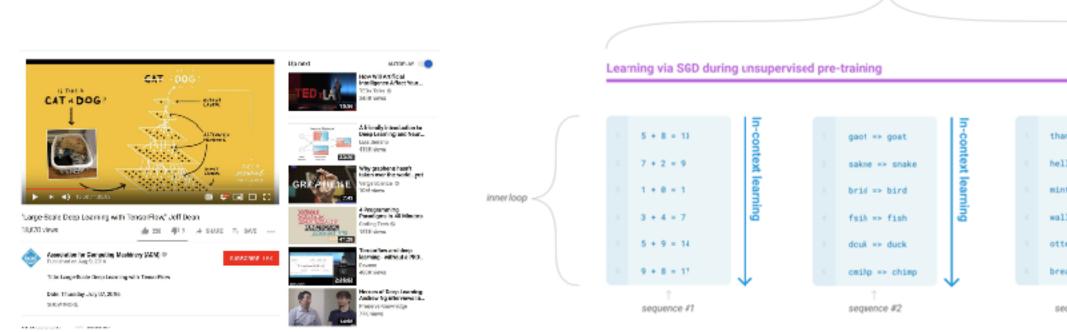
Topics

- Multi-task learning, transfer learning basics
- Meta-learning algorithms 2. (black-box approaches, optimization-based meta-learning, metric learning)
- Advanced meta-learning topics 3. (meta-overfitting, unsupervised meta-learning, Bayesian models)
- Unsupervised pre-training for few-shot learning 4.
- Relation to foundation models & in-context learning 5.
- 6. Domain adaptation & generalization
- Lifelong learning 7.
- 8. Open problems

Case studies of important & timely applications

- Multi-task learning in recommender systems
- Meta-learning for land cover classification, education
- Few-shot learning in large language models

Emphasis on deep learning techniques.



Zhao et al. Recommending What Video to Watch Next. 2019

Brown et al. Language Models are Few-Shot Learners. 2020





New last year: No reinforcement learning

- New course in Spring quarter (CS224R: Deep Reinforcement Learning)
- Removing RL makes the course more accessible.
- You can still explore RL topics in final project.

What if I want RL?

Lectures & Office Hours

Lectures

- In-person, livestreamed, & recorded
- Two guest lectures (TBD)
- Three TA-led tutorial sessions (Thursdays)

Ask questions!

- by raising your hand

Office hours

- mix of in-person and remote

Participation

- Opportunity for up to 2% extra credit (joining lectures, helping on Ed)

Pre-Requisites

Machine learning: CS229 or equivalent.

Some familiarity with deep learning:

- We'll build on concepts like backpropagation, recurrent networks
- Assignments will require training networks in **PyTorch**.
- Ansh will hold a PyTorch review session on Thursday, Sep 28, 3-4:20 pm in Gates B3.

e.g. we'll assume knowledge of SGD, cross-val, calculus, probability theory, linear algebra

Assignments

Homework 0: Multi-task learning basics **Homework 1**: Multi-task data processing, black-box meta-learning **Homework 2**: Gradient-based meta-learning & metric learning **Homework 3**: Fine-tuning pre-trained models

- **6 late days** total across: homeworks, project-related assignments maximum of 2 late dates per assignment
 - **Collaboration policy**: Please read course website & honor code.
- Document collaborators & write up HW solutions on your own. (incl. no Al tools)

5% of grade

15% of grade each

- Homework 4 (optional): Bayesian meta-learning & meta-overfitting (replaces 15% of HW or project)
 - Grading: 50% homework, 50% project



Research-level project of your choice

- in groups of **1-3 students**
- if applicable, encouraged to use your research!
- can share with other classes, with slightly higher expectation
- same late day policy as HWs (but no late days for poster)

Poster presentation on December 6th.

Final Project

We'll provide ~\$75 in Azure credits for HWs & project

Initial Steps

1. Homework 0 is out — due next Wednesday at 11:59 pm PT 2. Start forming final project groups if you want to work in a group

The Plan for Today

1. Course goals & logistics 2. Why study multi-task learning and meta-learning?

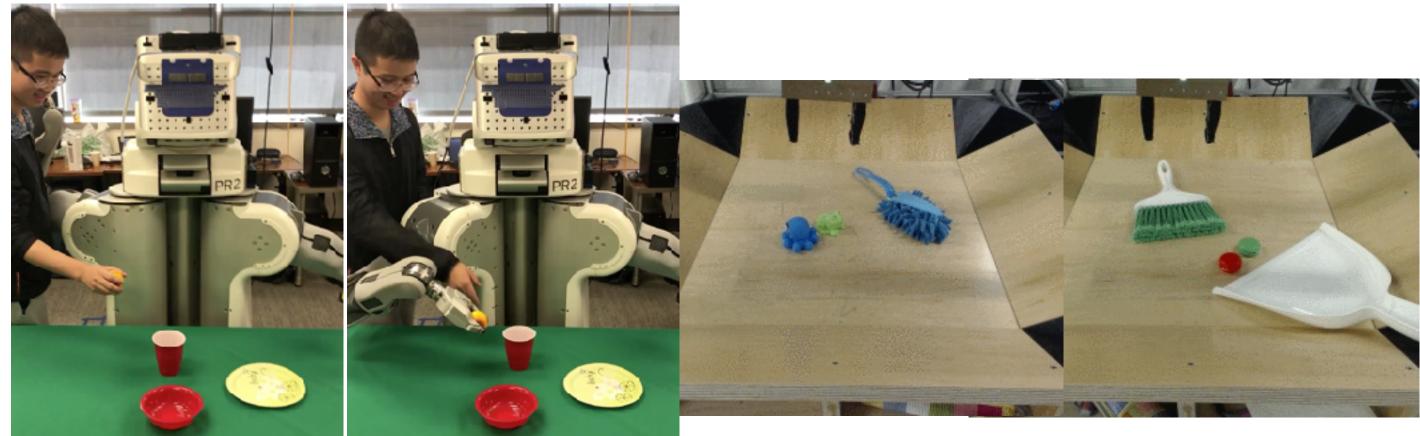
Some of Chelsea's Research (and why I care about multi-task learning and meta-learning)

How can we enable agents to learn a breadth of skills in the real world?

Robots.



JMLR'16



Why robots?

must generalize across tasks, objects, environments, etc

need some common sense understanding to do well

supervision can't be taken for granted

Yu*, Finn*, Xie, Dasari, Zhang, Abbeel, Levine, RSS '18

Xie, Ebert, Levine, Finn, RSS '19

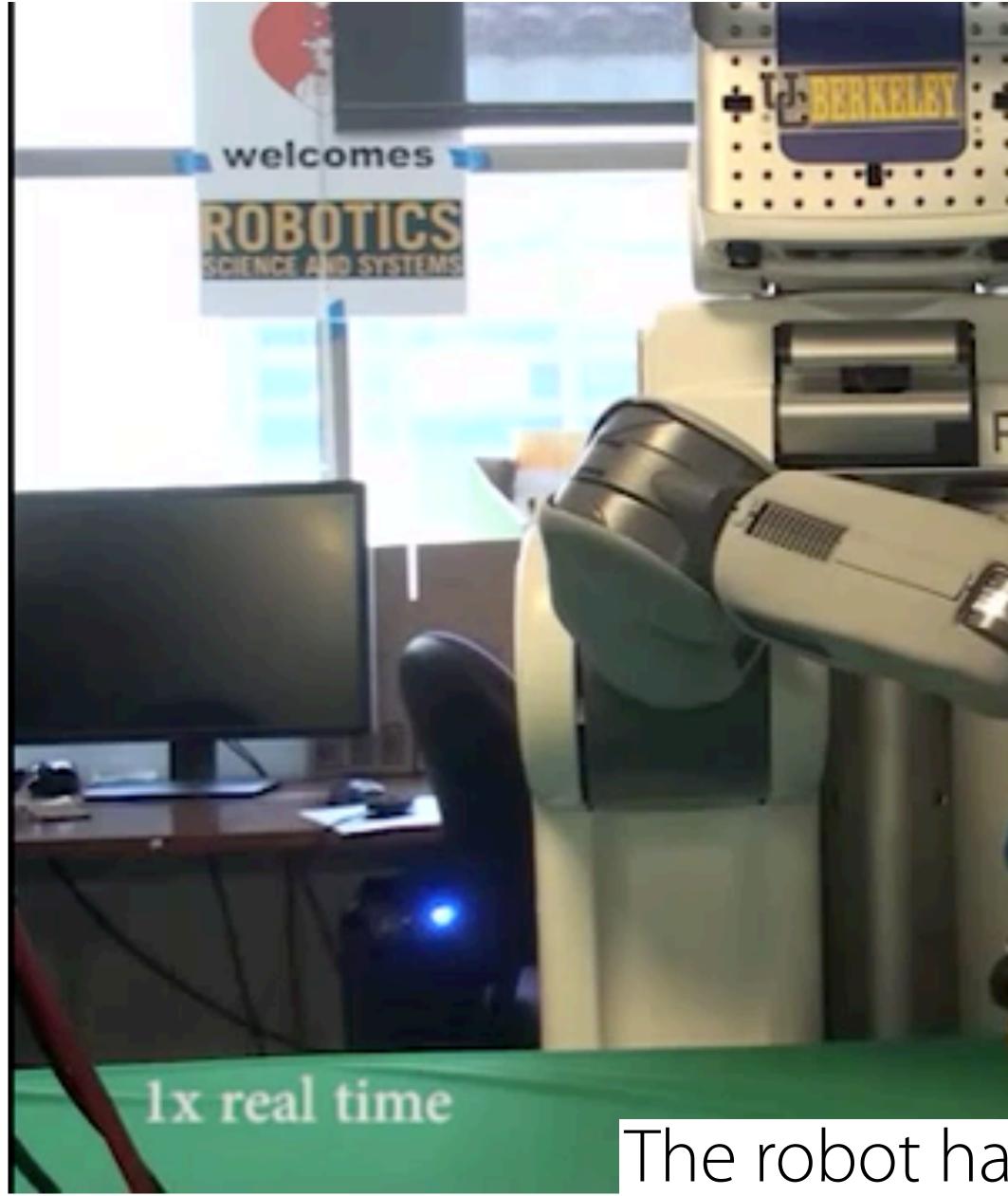
Robots can teach us things about intelligence.

faced with the **real world**

16



Beginning of my PhD



PR2 autonomous execution

The robot had its eyes closed.

Levine et al. ICRA '15





autonomous execution Levine*, Finn* et al. JMLR'16

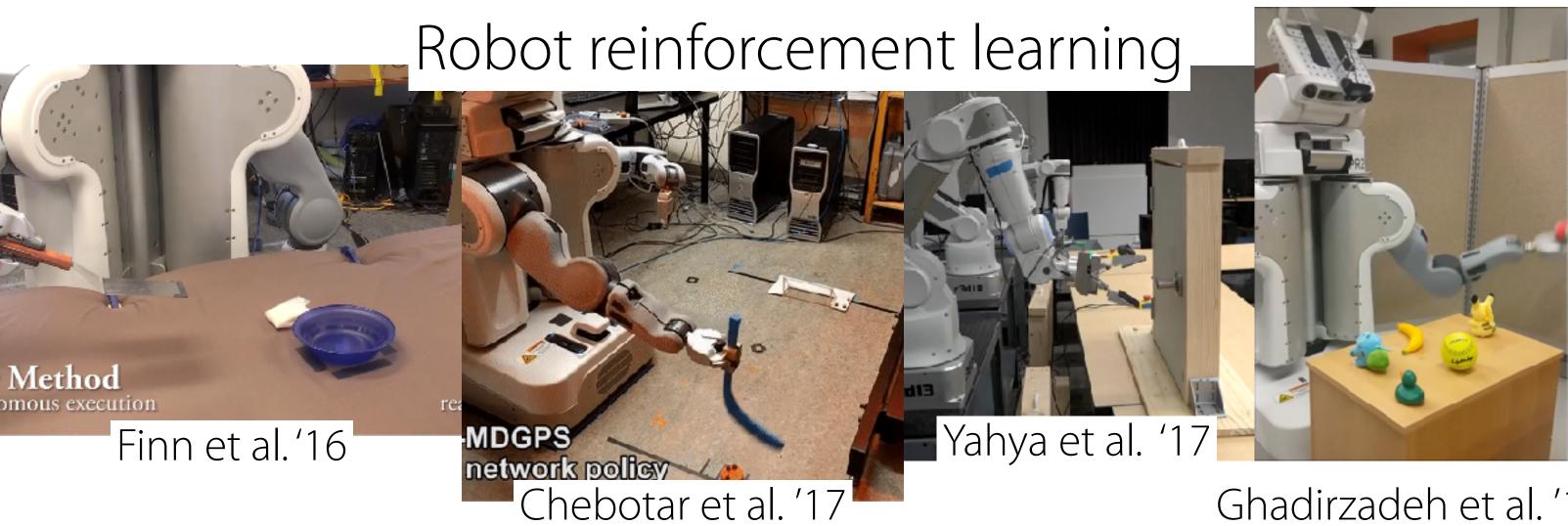




Our Method autonomous execution

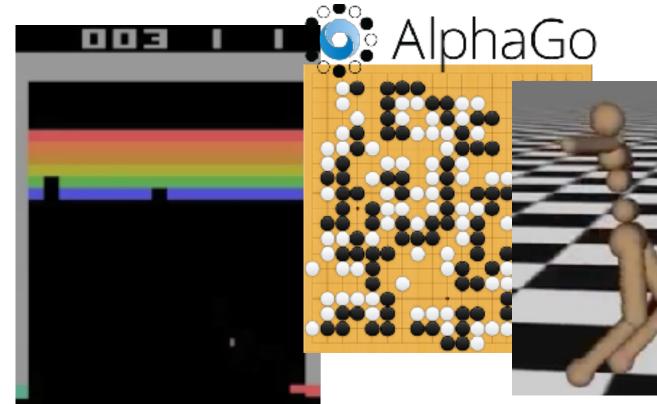






Learn one task in one environment, starting from scratch

Reinforcement learning



Ghadirzadeh et al. '17

Atari

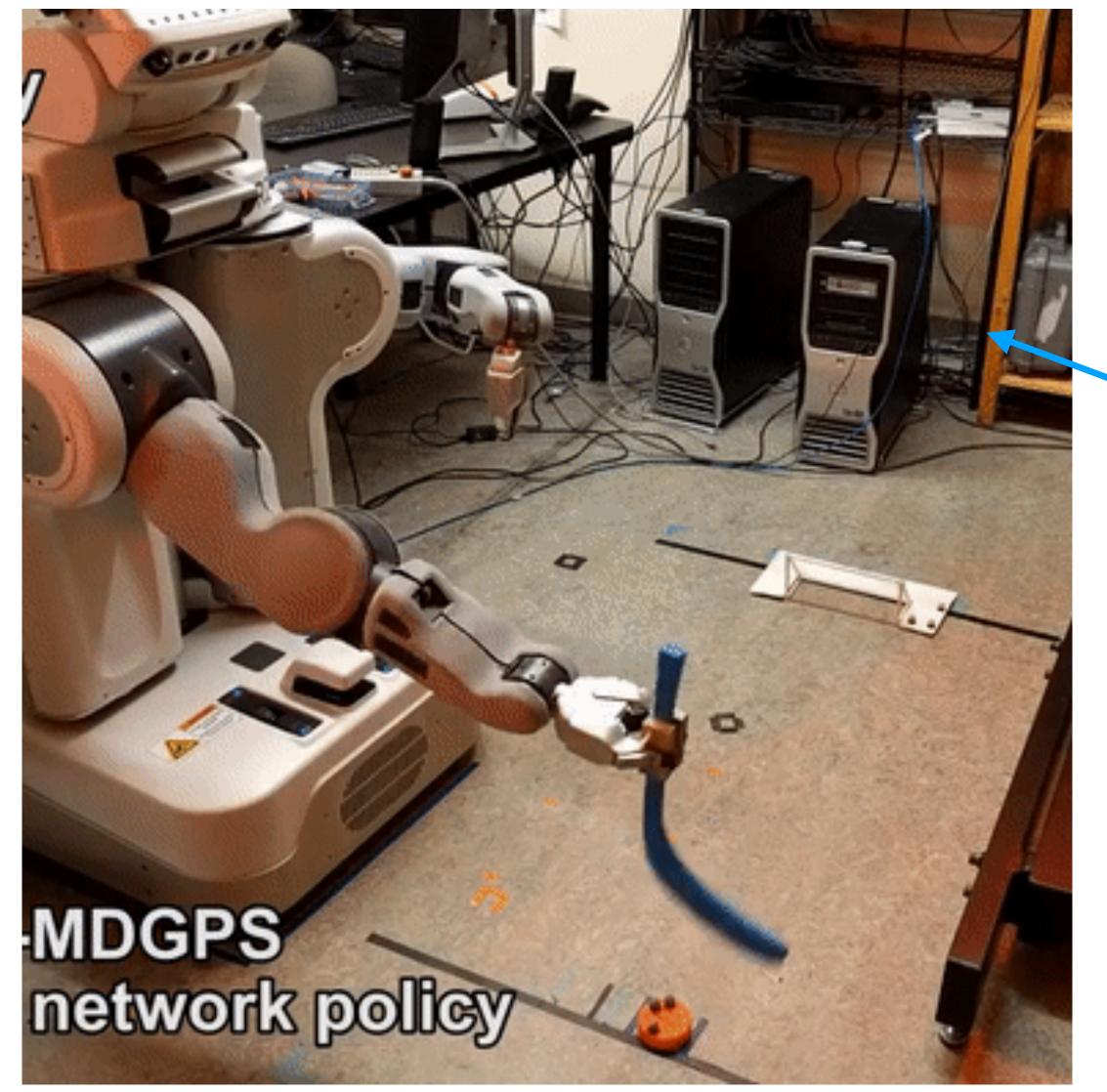
locomotion





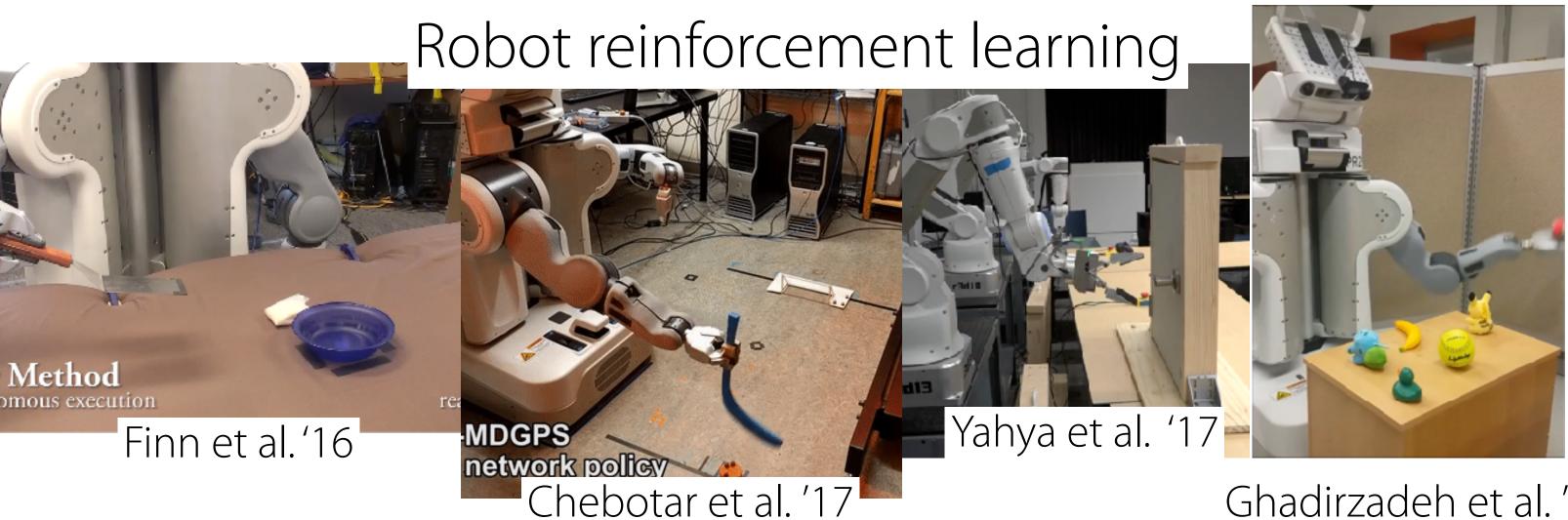


Behind the scenes...





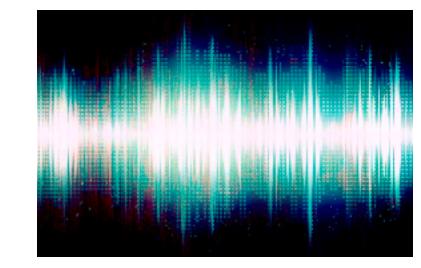
Yevgen is doing more work than the robot! It's not practical to collect a lot of data this way.



Learn one task in one environment, starting from scratch using **detailed supervision**

Not just a problem with reinforcement learning & robotics.

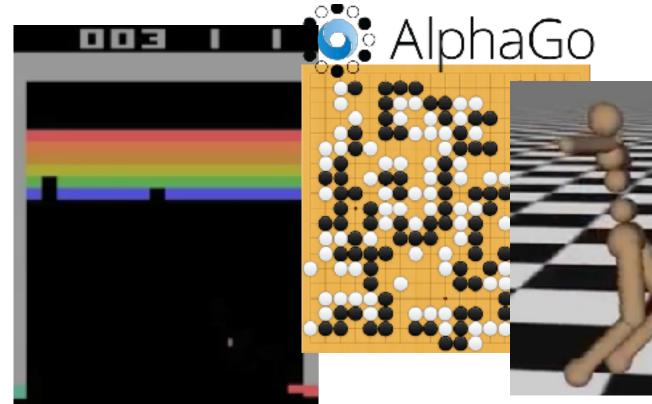




object detection

machine translation speech recognition More diverse, yet still one task, from scratch, with detailed supervision

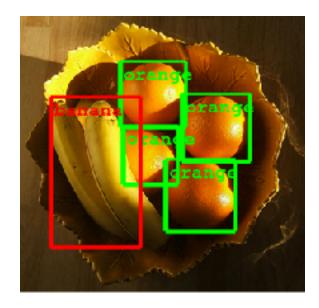
Reinforcement learning



Ghadirzadeh et al. '17

Atari

locomotion





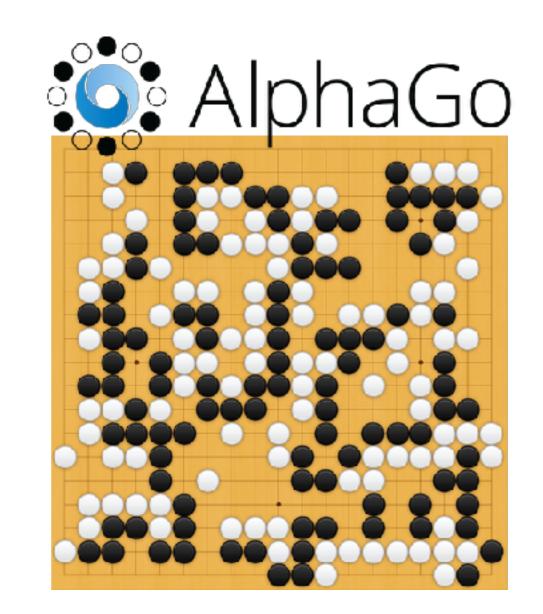






Source: <u>https://youtu.be/8vNxjwt2AqY</u>







VS.

Source: <u>https://i.imgur.com/hJIVfZ5.jpg</u>



Why should we care about multi-task & meta-learning? ... beyond the robots and general-purpose ML systems



Why should we care about multi-task & meta-learning? ... beyond the robots and general-purpose ML systems

deep



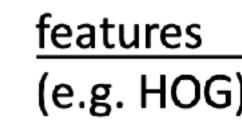
Standard computer vision: hand-designed features

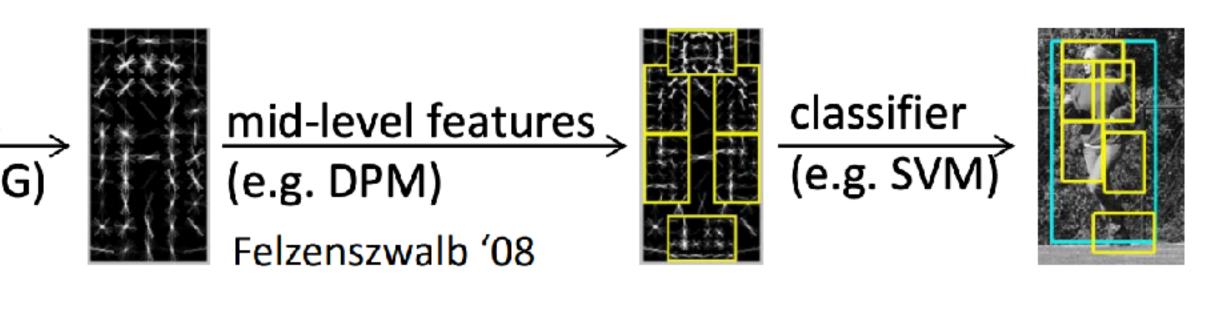
Modern computer vision: end-to-end training

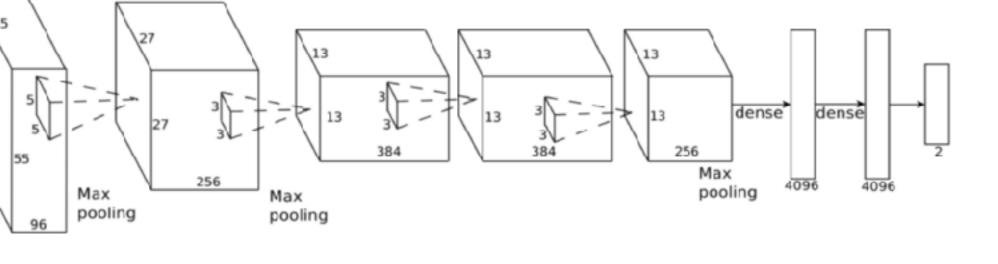
Slide adapted from Sergey Levine







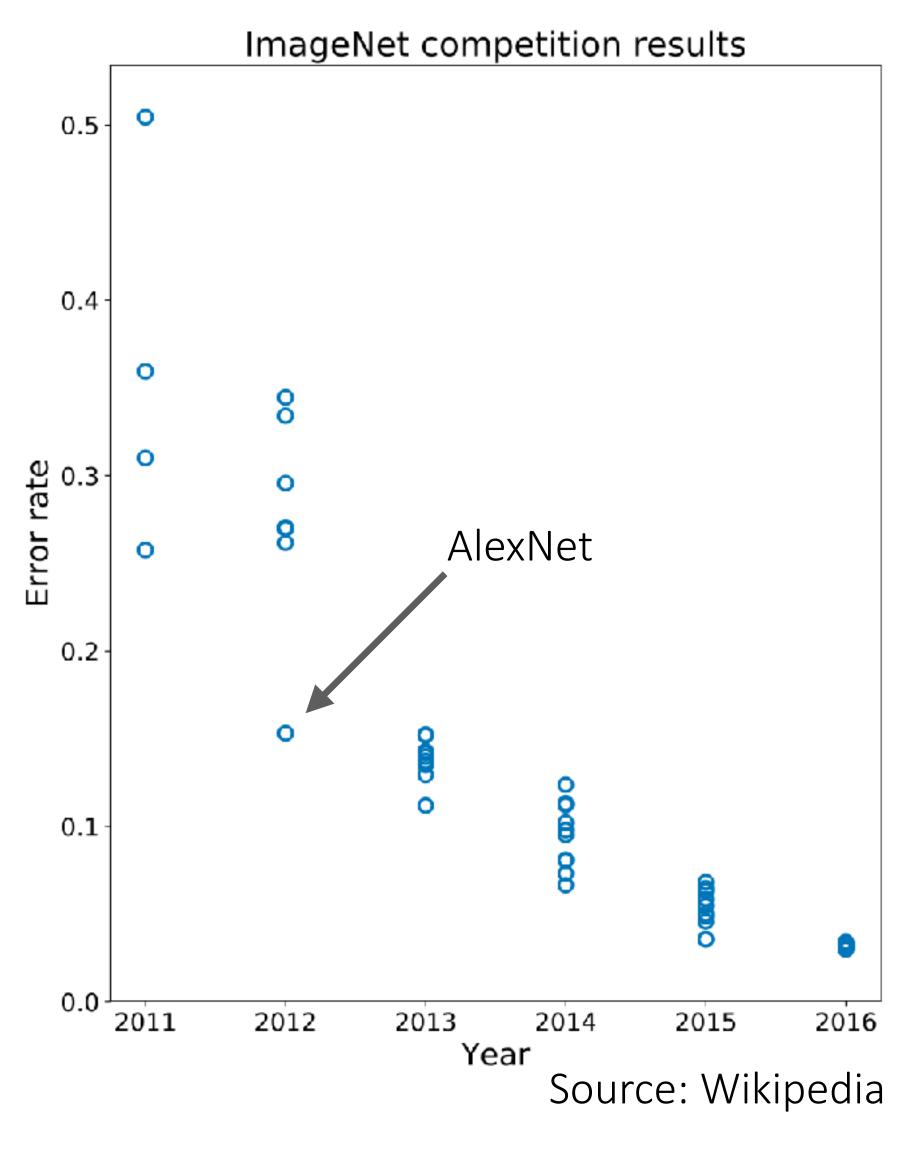




Krizhevsky et al. '12

Deep learning allows us to handle *unstructured inputs* (pixels, language, sensor readings, etc.) without hand-engineering features, with less domain knowledge

Deep learning for object classification



Why deep **multi-task** and **meta-learning**?

Deep learning for machine translation

Google's Neural Machine Translation System: Bridging the Gap between Human and Machine Translation

Yonghui Wu, Mike Schuster, Zhifeng Chen, Quoc V. Le, Mohammad Norouzi yonghui,schuster,zhifengc,qvl,mnorouzi@google.com

	PBMT	GNMT	Human	Relative
				Improvement
$English \rightarrow Spanish$	4.885	5.428	5.504	87%
$\mathbf{English} \to \mathbf{French}$	4.932	5.295	5.496	64%
$\mathbf{English} \to \mathbf{Chinese}$	4.035	4.594	4.987	58%
$\text{Spanish} \to \text{English}$	4.872	5.187	5.372	63%
$French \rightarrow English$	5.046	5.343	5.404	83%
$\mathbf{Chinese} \to \mathbf{English}$	3.694	4.263	4.636	60%

Table 10: Mean of side-by-side scores on production data

Human evaluation scores on scale of 0 to 6

PBMT: Phrase-based machine translation

GNMT: Google's neural machine translation (in 2016)



Large, diverse data (+ large models)



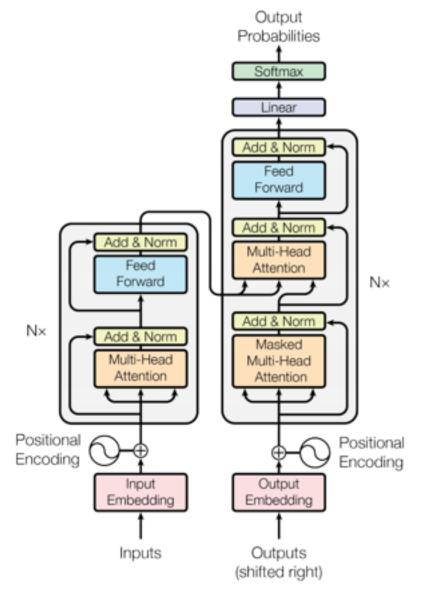
Russakovsky et al. '14

What if you don't have a large dataset?

medical imagine robotics in the second secon

Broad generalization

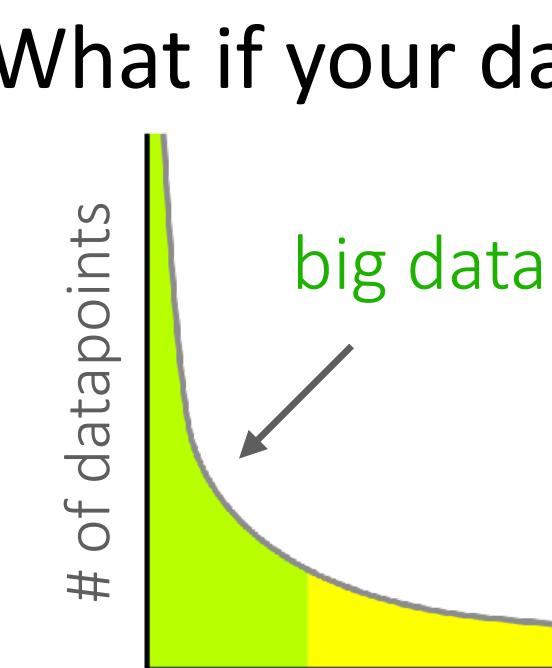






Vaswani et al. '18

Wu et al. '16



objects encountered interactions with people words heard driving scenarios

This setting breaks standard machine learning paradigms.

What if your data has a long tail?

small data

What if you need to quickly learn something new? about a new person, for a new task, about a new environment, etc.

training data Braque Cezanne













test datapoint



By Braque or Cezanne?

What if you need to quickly learn something new? about a new person, for a new task, about a new environment, etc.

"few-shot learning"

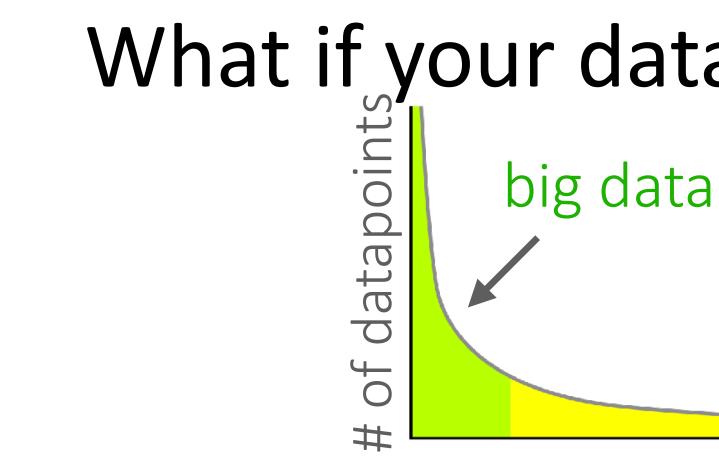




How did you accomplish this? by leveraging prior experience!

What if you want a more general-purpose Al system? Learning each task from scratch won't cut it.

What if you don't have a large dataset? robotics medical imaging translation for rare languages



What if you need to quickly learn something new? about a new person, for a new task, about a new environment, etc.

This is where elements of multi-task learning can come into play.

personalized education,

medicine, recommendations

What if your data has a long tail?

small data



Why now?

Why should we study deep multi-task & meta-learning now?

Multitask Learning^{*}

RICH CARUANA

Multitask Learning (MTL) is an inductive transfer mechanism whose principle goal is to improve generalization performance. MTL improves generalization by leveraging the domain-specific information contained in the training signals of *related* tasks. It does this by training tasks in parallel while using a shared representation. In effect, the training signals for the extra tasks serve as an inductive bias. Section 1.2 argues that inductive transfer is important if we wish to scale tabula rasa learning to complex, real-world tasks. Section 1.3 presents the simplest method we know for doing multitask inductive transfer, adding extra tasks (i.e., extra outputs) to a backpropagation net. Because the MTL net uses a shared hidden layer trained in parallel on all the tasks, what is learned for each task can help other tasks be learned better. Section 1.4 argues that it is reasonable to view training signals as an inductive bias when they are used this way.

Caruana, 1997

Is Learning The *n*-th Thing Any Easier Than Learning The First?

Sebastian Thrun¹

They are often able to generalize correctly even from a single training example [2, 10]. One of the key aspects of the learning problem faced by humans, which differs from the vast majority of problems studied in the field of neural network learning, is the fact that humans encounter a whole stream of learning problems over their entire lifetime. When faced with a new thing to learn, humans can usually exploit an enormous amount of training data and experiences that stem from other, related learning tasks. For example, when learning to drive a car, years of learning experience with basic motor skills, typical traffic patterns, logical reasoning, language and much more precede and influence this learning task. The transfer of knowledge across learning tasks seems to play an essential role for generalizing accurately, particularly when training data is scarce.

Thrun, 1998

On the Optimization of a Synaptic Learning Rule

Yoshua Bengio Jocelyn Cloutier Jan Gecsei Samy Bengio

Université de Montréal, Département IRO

This paper presents a new approach to neural modeling based on the idea of using an automated method to optimize the parameters of a synaptic learning rule. The synaptic modification rule is considered as a parametric function. This function has *local* inputs and is the same in many neurons. We can use standard optimization methods to select appropriate parameters for a given type of task. We also present a theoretical analysis permitting to study the *generalization* property of such parametric learning rules. By generalization, we mean the possibility for the learning rule to learn to solve new tasks. Experiments were performed on three types of problems: a

Bengio et al. 1992

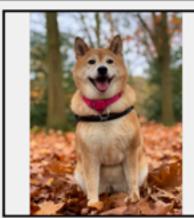


These methods are continuing to play a major role in Al.

Object recognition:



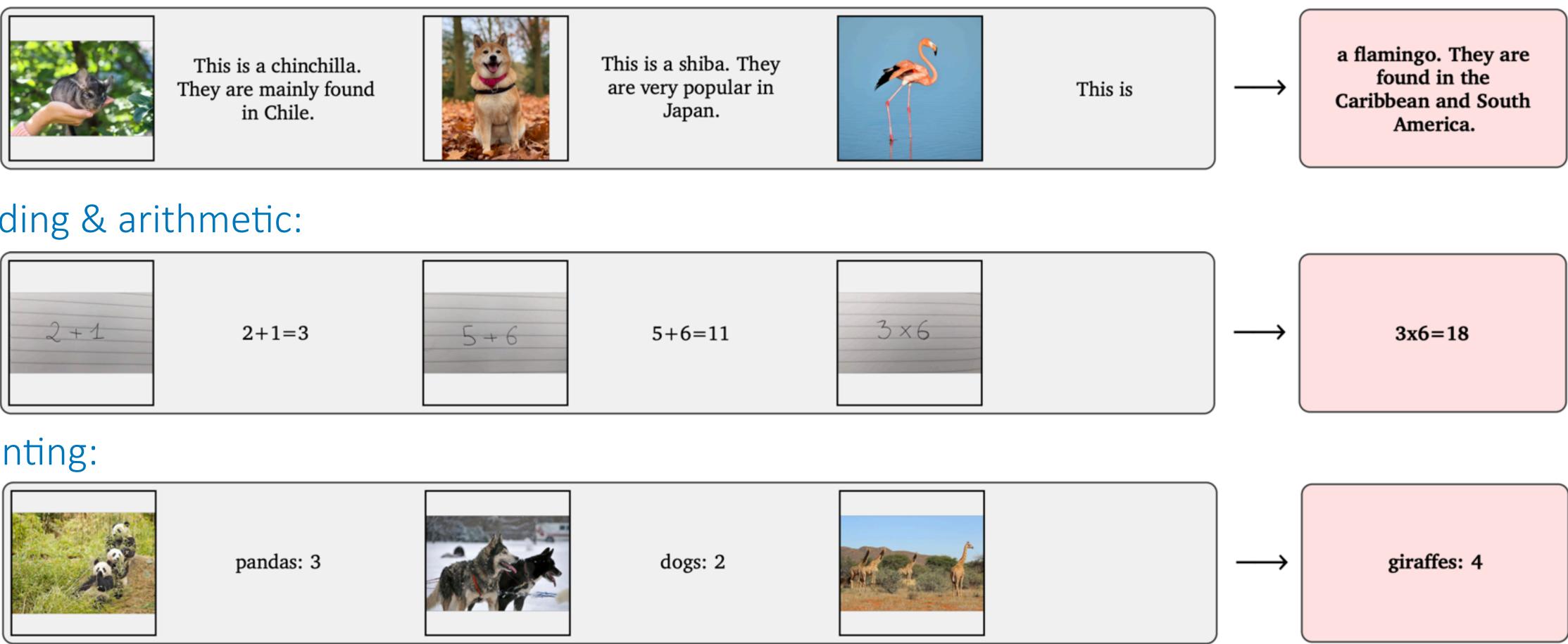
in Chile.



Reading & arithmetic:

2+1 2+1=3	5+6	5+6=11
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Counting:



Alayrac*, Donahue*, Luc*, Miech* et al. Flamingo: a Visual Language Model for Few-Shot Learning. 2022

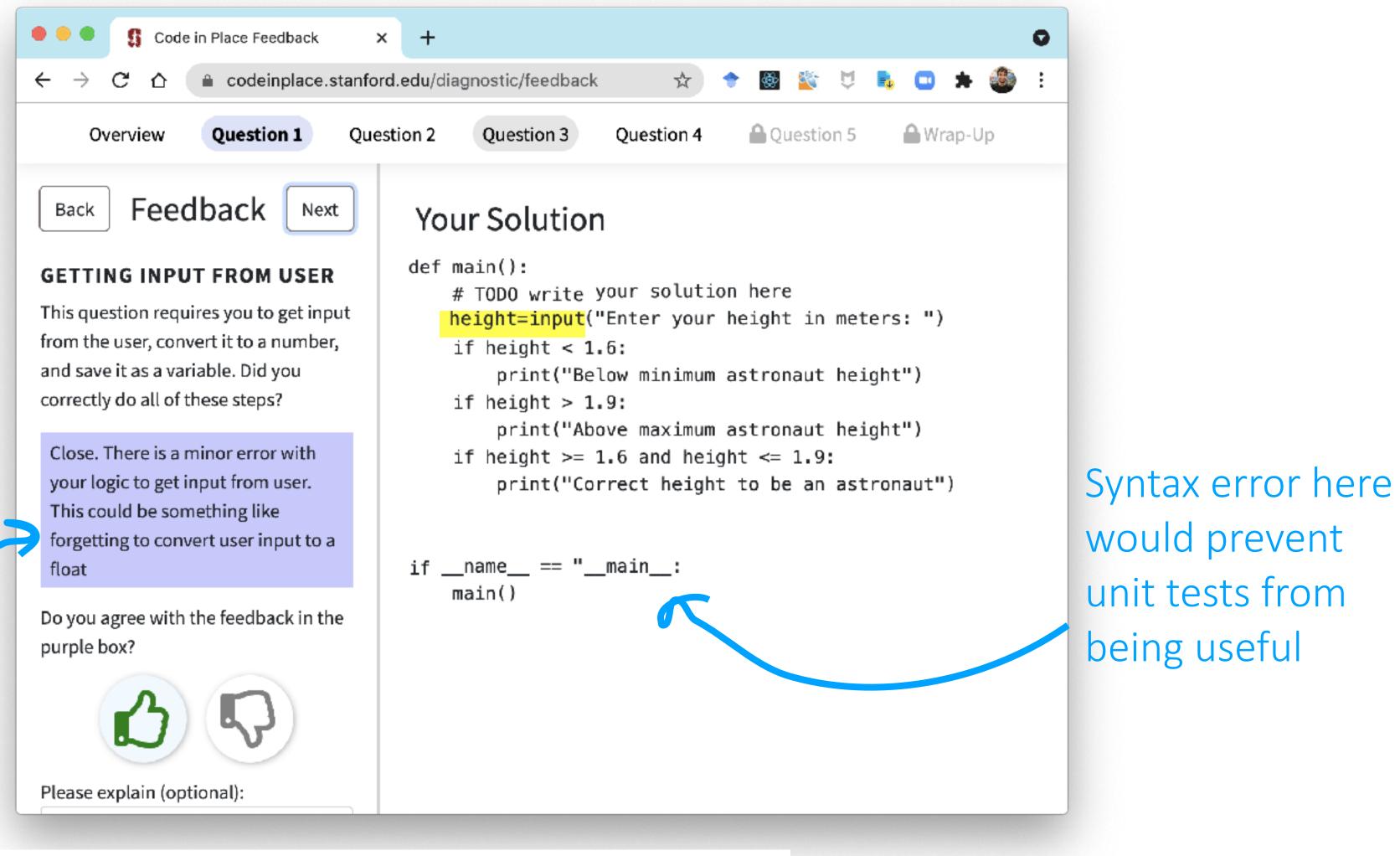
Visual language models can learn many distinct tasks.

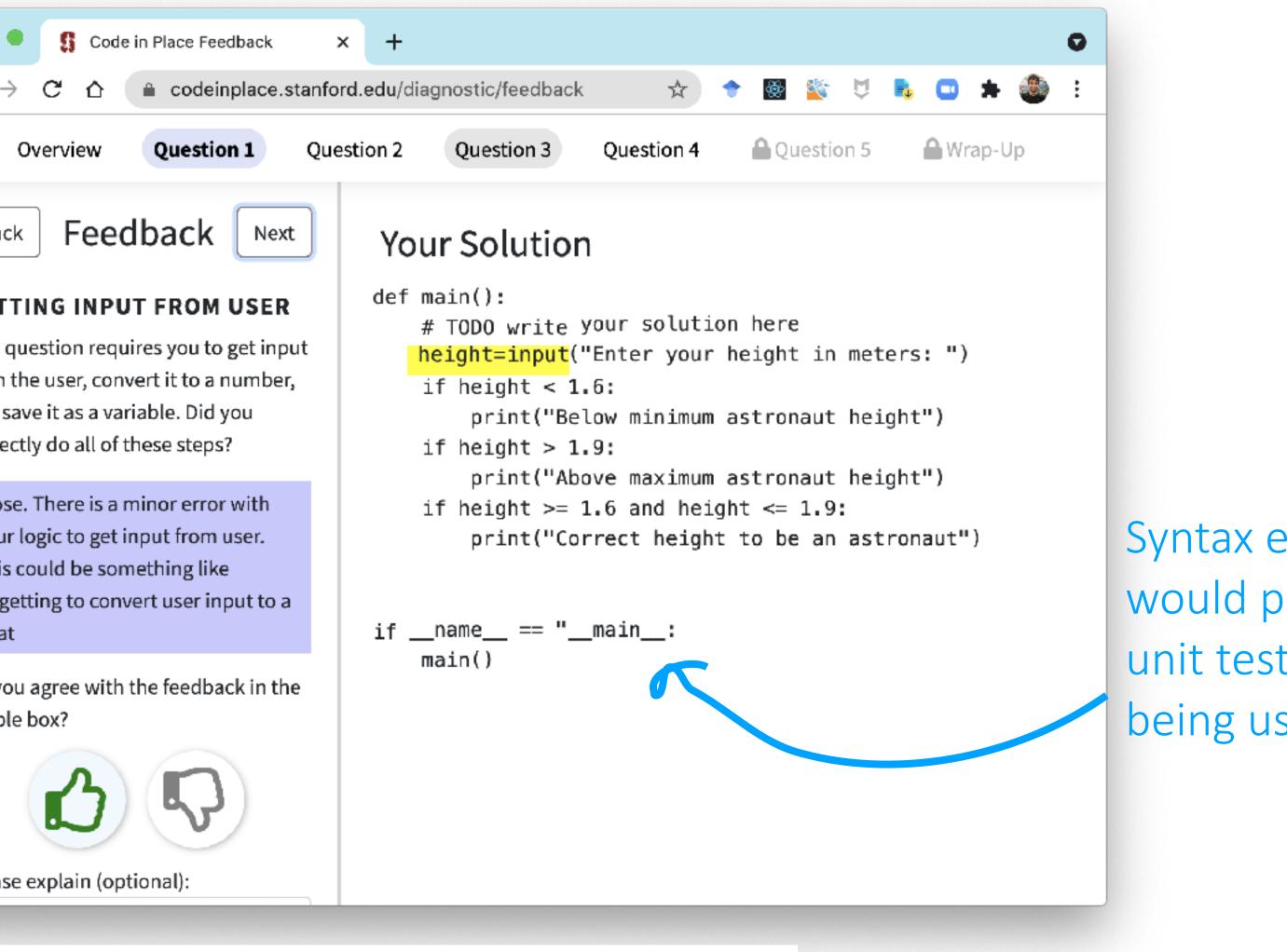
These methods are continuing to play a major role in Al.

Code-in-Place 2021

Humans gave feedback on ~1k student programs. Meta-learning system gave feedback on the remaining ~15k.

> Generated feedback





Wu, Goodman, Piech, Finn. ProtoTransformer: A Meta-Learning Approach to Providing Student Feedback. 2021

Meta-learning enables automatic feedback on student work on new problems.



These methods are continuing to play a major role in Al.

Multilingual machine translation

Meta

Introducing the First AI Model That Translates 100 Languages Without Relying on English

October 19, 2020 By Angela Fan, Research Assistant

 M2M-100 is trained on a total of 2,200 language directions — or 10x more than previous best, English-centric multilingual models. Deploying M2M-100 will improve the quality of translations for billions of people, especially those that speak low-resource languages.

Fan et al. JMLR, 2021

A Generalist Agent Reed et al. TMLR 2022



YouTube recommendations

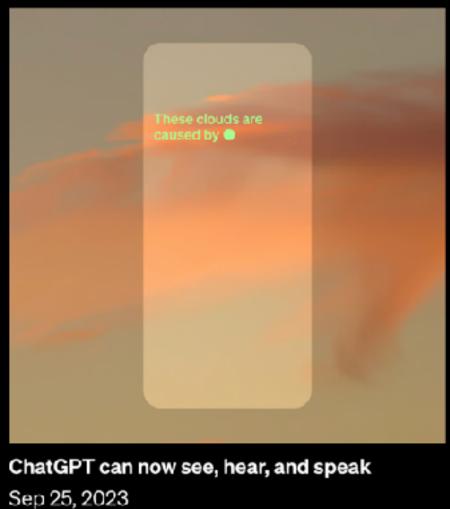
Recommending What Video to Watch Next: A Multitask Ranking System

Zhe Zhao, Lichan Hong, Li Wei, Jilin Chen, Aniruddh Nath, Shawn Andrews, Aditee Kumthekar, Maheswaran Sathiamoorthy, Xinyang Yi, Ed Chi Google, Inc. {zhczhao,lichan,liwci,jilinc,aniruddhnath,shawnandrcws,aditcek,nlogn,xinyang,cdchi}@googlc.com

In this paper, we introduce a large scale multi-objective ranking system for recommending what video to watch next on an industrial video sharing platform. The system faces many real-world challenges, including the presence of multiple competing ranking objectives, as well as implicit selection biases in user feedback. To

RecSys 2019

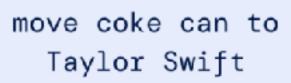
GPT-4V



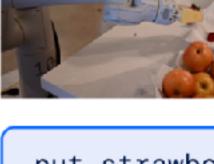
Trance?

Zero-shot robot generalization RT-2 Brohan et al. 2023





pick up the bag about to fall off the table

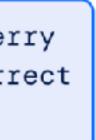


put strawberry into the correct bowl

One-shot imitation from humans







Its success is important for the democratization of deep learning.

ImageNet

WMT '14 English - French

Switchboard Speech Dataset

Kaggle's Diabetic Retinopathy Detection dataset

Adaptive epilepsy treatment with RL Guez et al. '08

Learning for robotic manipulation Finn et al. '16 1.2 million images and labels

40.8 million paired sentences

300 hours of labeled data

dataset 35K labeled images

< 1 hour of data

< 15 min of data

But, we also still have many open questions and challenges!

What is a task?

$\begin{array}{c} \text{dataset } \mathcal{D} \\ \text{loss function } \mathcal{L} \end{array} \longrightarrow \text{model } f_{\theta} \end{array}$ Informally:

Different tasks can vary based on:

- different objects
- different people
- different objectives
- different lighting conditions
- different words

. . .

- different languages

What is a task?

Not just different "tasks"

Critical Assumption

The bad news: Different tasks need to share some structure. If this doesn't hold, you are better off using single-task learning.

The good news: There are many tasks with shared structure!





- Even if the tasks are seemingly unrelated:



- The laws of physics underly real data. - People are all organisms with intentions.

- The rules of English underly English language data.

- Languages all develop for similar purposes.

This leads to far greater structure than random tasks.



Informal Problem Definitions We'll define these more formally later.

The multi-task learning problem: Learn a set of tasks more quickly or more proficiently than learning them independently.

The transfer learning problem: Given data on previous task(s), learn a new task more quickly and/or more proficiently.

This course: anything that solves these problem statements.

Doesn't multi-task learning reduce to single-task learning?

$\mathcal{D} = \bigcup \mathcal{D}_i$

$$\mathcal{L} = \sum \mathcal{L}_i$$

Are we done with the course?

Doesn't multi-task learning reduce to single-task learning?

Yes, it can!

Aggregating the data across tasks & learning a single model is one approach to multi-task learning.

But, what if you want to learn *new* tasks?

And, how do we tell the model what task to do?

And, what if aggregating doesn't work?



1. Homework 0 is out

Next time (Mon): Multi-Task Learning Basics

Reminders

2. Start forming final project groups if you want to work in a group